## R.D. Iuce: ALGEBRATS SYSTEMS OR MRASURMMENT

(sumerized by J. de Leeuw)

## 1. Extensive ieasurement

The major problen of tine foundations of measurement is to find axiomatic systerns that permit the construction of homomorphic mappings of a given empirical relatjonal systam, which satisfies the axioms, into an appropriate numerical system, which also satisfies the axioms. In these lectures, the numerical system will always be a subset of the set of real numbers, Re.Of course, such empirical relationai sifitems are of scientiric interest only if there is at least one interpretation for which the axioms are (approximate) empirical laws. In those cases, the numerical represertation summarizes these laws in a way that it is easy both to remember and to maku valid deductions. The simplest structure for which measurement-theoretical considerations are possible is the system $\langle A, \geqslant\rangle$, whers $A$ is an arbitrary set and $\geqslant$ is some ordering relation. \#le shall suppose that $\geqslant$ is a weak order, i.e. $\geqslant$ satisfies
i) for ail $x \in A, \quad x \geqslant x \quad$ (reflexivity
ii) for all $x, y, z \in A$, if $x \geqslant y$ and $y \geqslant z$, then $x \geqslant z$ (transitivity)
iii) for $\varepsilon l l y, y \in A$, either $x \geqslant y$ or $y \geqslant x$ or both (connectociyess)

In the usual way, define the strict ordering $>$ by

$$
x>y \quad \text { iff } x \geqslant y \text { and } \operatorname{not}(y \geqslant x)
$$

and the indifference relation $\sim$ by

$$
x \cap y \text { iff } x \geqslant y \text { and } y \geqslant x
$$

It is easily shown that $>$ is a strict simple order and that $\sim$ is an equivalence relation when $\geqslant$ is a weak order. The representation theorem for a weak ordering answers the question: under what conditions is there a homomorphic mapping of $A$ into a subset of Re? To formulate the answer, we need the following definition: a subset $B$ of a set $A$ is called order-dense in $A$ if for all $x, y \in A$ and $\notin B$, there exists an element $b \in B$, such thai $x \geqslant b \geqslant y$. Then the answer is given by the

## Cantor-Birkhoff theorem:

Theorem 1.1: Suppose that $\left.\left\langle A_{2}\right\rangle\right\rangle$ is a weak ordered structure. There exists a function $\mathrm{f}_{2}$ chat maps A into Re nonotonically, i.e.,

$$
x \geqslant y \text { iff } f(x) \geqslant f(y),=\text { or all } x, y \in A,
$$

iff A contains a countable order-dense subse.t.

A sketch of a proof of this representation theorem can be found in Birkhofi (1967, p. 200; it is rot quite correct: B must include the erd points of all gaps). The most familiar example of a countable order-dense subset is, of course, the set of rationai numbers considered as a subset of the reals. The uniqueness th3orem for the case under consideration is as follows:

Theorem 1.2: If $f$ and $f^{\prime}$ are both homomozphisms of $\langle A, \geqslant\rangle$ into the reals, then there is a strictly monotonic increasing numerical function $\psi$ such that $f=\psi\left(f^{\prime}\right)$, i.e., the representation forms an ordinal scale.

This uniqueness theorem shows that a numerical representation of $\langle A, \geqslant\rangle$ has a considerable lack of invariance. Scientifically this is an obvious disadvantage (it renders classical analytic techniques nearly useless) and that makes systems of this simplicity of little interest. In general, however, the data include moze information than juitt a weak oracring of an abstract set. By using this additional informavion, we attempt to strengthen the invariance of the repiesentation.

Our first example of addэd structure is the introduction of a binary operation, written as 0 . The theory of such systems $\langle A, \geqslant, 0\rangle$ is called extensive measureinent. The empirical situation is familiar from and important for physics. We heve a set of objects $A$; these obiects can be compared with each other, and they can be concatenated. Examples are length, mass, and time. In the reasurement of mass we can put two different objects $x$ and $y$ in the pans of a pan balance (in a vacuum) and sstablish, by notin ${ }_{0}$ which, if either, pan drops, whether $x>y, y>x$ or $x \sim y$. Moreover, we can put two dif:erent objects $x$ and $y$ in the same pan and study their combined effect, xoy.

Althovgh the direct significance of extensive aeasurement for psychology is limited, the nathematics involved is funcamental for all other measurement systems.

In classical theories of extensive measurement, it is assumed that the system is clozed under the binary operation 0 , i.e.

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if x,y\inA, then xcy, yox \inA.
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In practice, however, unrestricted concatenation causes trouble (it would, for exemple, residit in the ultimate destruction of any pan balance). Observe, uorcover, that in probabiiity theory we have $p(A \cup B)=p(A)+p(B)$ when, and only when, $A$ and $B$ are disjoint events. This means that urior of disjoint sets is very much like concatenation, but clearly wesetricted concatenetior (unions) is not acceptable. To overcome tnese objections, we add to the sysiem a set (relation) B that tormulates the restrictions on concatenation. $B$ is a subset of $A \times A$, Veroaliy, $w=$ interpret $(x, y) \in E$ to mean that $x$ and $y$ can be concatenatod.

The axioms for (generalized) extensive $\mathbb{H}$ ersurement are the following:

$$
\begin{aligned}
& \text { i) }\langle A, \geqslant\rangle \text { is a reakly orderea set } \\
& \text { ii) } B \subseteq A x A \text { and } B \neq \varnothing \\
& \text { iii) } 0: B \rightarrow A \\
& \text { iv) if }(x, y) \in B \text { and } x \geqslant x^{\prime} \text { and } y \geqslant y^{\prime}, \text { then }\left(x^{\prime}, y^{\prime}\right) \in B \\
& \text { v) if }(x, y) \in B,(x o y, z) \in B, \text { then }(y, z) \in B \text { and }(x, y o z) \in B \text { and } \\
& \text { (xoy) } o z \backsim x o(y o z)
\end{aligned}
$$

vi) if $x \geqslant y$ and $(x, z) \in B$, then $x o z \geqslant y o z$ and $z o x \geqslant z o y$

Observe, that, by the third axiom, the system is closed under o iff $B=A \times A$. Axiom iv) forces a certain structure on the system, one that is piausible both for probability and for mass. In the latter case, it says: if two weights don't break the balance, then two lesser weights won't either. Axiom $v$ ) asserts that the operation 0 is associative provided that the relevant elements can be combined at all, and axiom vi) shows that the ordering is compatible with the operation O. A system $\langle A, B, \geqslant, 0\rangle$ that satisfies axioms $i$ )-vi) is called a weakly-ordered local semigroup. Such a semigroup is called positive if, in addition to i)-vi), we have
vii) for $2 l l(x, y) \in B, x o y>x$ and $x o y>y$.

It is called solvable if in addition
viii) if $x>y$, then there exists $a z \in A$, with $(y, z) \in B$ and $x \sim y o z$. Finally, in most measurement ${ }^{+}$systems, we need an Archimedean axiom. This axiom is named after a property of the real numbers: if $\mathrm{I}^{-1}$ is the set of positive integers and if $\alpha, \beta$ are positive reals, then the set $\left\{n \mid n \in I^{+}\right.$and $\left.\beta \geqslant n \alpha\right\}$ is finite. To use a similar axiom in our context we need the notion of $n$ copies of an element of $A$. We define $n x$ by induction:
a) $1 x=x$,
b) if $(n-1) x \in A$ and $((n-1) x) \in B$, then $n x=(n-1) x o x$,
and we state the Archimedean axiom as follows:
ix) for all $x, y \in A$, the set $\left\{n \mid n \in I^{+}, n x\right.$ is defined and $y \geqslant n x\}$ is finite.

Now we can state the representation and uniqueness theorems for extensive measurement with restricted concatenation.

Theorem 1.3: If $\left\langle A, B_{2} \geqslant, 0\right\rangle$ is a positive, solvable, Archimedean, weakly-ordered local semigroup, then there exists a function from A into $\mathrm{Re}^{+}$, such that
i) $x \geqslant y$ eff $f(x) \geqslant f(y)$,
ii) if $(x, y) \in B$, then $f($ xor $)=f(x)+f(y)$,
iii) if $f^{\prime}$ is another function that satisfies i) and ii), then there exists a positive number $\alpha$ such that for all nonmaximal elements $x$ in $A, f(x)=\alpha_{f}^{\prime}(x)$. (An element $x$ of $A$ is maximal if $x \geqslant y$ for all $y \in A_{0}$ )

Axioms i) -ix) can be classed in two groups. In the first, we have those that are necessary in terms of the representation. They simply follow from the fact that a representation with the properties mentioned in the theorem exists. This group includes axioms i), v), vi.), vii) and ix). The second group of non-necessary properties are called structural conditions; they are only sufficient and not necessary for the representation to exist. This group includes the axioms ii), iii), and iv) that describe the structure of the set $B$,
and the solvability axiom viii) that asserts that certain equations can be solved.

Whether or not these axioms can and/or must be tested empirically is a subtle problem. In physics the solvability axiom viii), the positivity axiom vii), and the weak order axiom i) are assumed to holld for idealized measuring instruments and an idealized set of objects. Violations are ascribed to friction of the pan balance and other imperfections of the empirical situation. In psychology, the violations of axiom i) may be more serious, because we do not always have a clear idea of what "ideal" would mean. Intransitivity of preference and, especially, of indifference are common phenomena. One would like to have a suitable statistical model to test hypotheses and to assess the seriousness of these violations, but in the area of İundamental measurement problems no satisfactory statistical procedures are now available.

Theorem 1.3 is a generalization of a classical theorem of Holder: An Archimedean simply ordered group is isomorphic to a subset of the additive reals. In this case $o$ is assumed to be a closed group operation, i.e. $\dot{B}=A \times A, O$ is associative, and identity and inverses exist. The existence of inverses makes the solvability axiom viii) unnecessary, since $x=y o\left(y^{-1} o x\right)$. We retain the important "compatibility" axiom vi) and also the Archimedean axiom ix).

A proof of Theorem 1.3 follows these lines: for $x, y \in A$, let $\mathbb{N}(x, y)$ be the largest integer for which both $\mathbb{N}(x, y) x$ is defined and $y \geqslant N(x, y) x$. Such an integer exists by the Archimedean axiom. We distinguish two cases. In the first, $A$ has a leasi element, $X_{0}$, relative to the given order $\geqslant$. It is easily shom that $y \sim \operatorname{li}\left(x_{0}, y\right)_{0}$ or, in words, y can be exactly reached by concatenating a finite number of copies of $x_{0}$. In this case, set $f(y)=i\left(x_{0}, y\right)$, and it can be show without great difficulty to have the desired representation properties. In the second case, we assume that $A$ has no least element. With $x$ fixed and $y, z \in A$, consider. the ratio $N(x, y) / \mathbb{N}(x, z)$. The numerator tells how many copies of $x$ are approximately equal to $y$, and the denominator tells the same thing for $z$. If we take $x$ smaller and smaller, which is possible since, by hypothesis, there is no least element, the approximations to $y$ and $z$ become better and better. In fact, it can be proved (by standard inequality techniques) that the relevant limit exists, and we define

$$
\frac{f(y)}{f(x)}=\operatorname{Lim}_{X \downarrow} \frac{\mathbb{N}(x, \tilde{j})}{\mathbb{N}(x, z)} .
$$

The resulting mapping $f$ is then shown to have the asserted properties, with axiom vi) playing a most important role. An important feature of this constructive proof is the use of a siandard series, which consists of the set of integral multiples of a certain "small" element, to approximate other elements. Whenever we use Holdertype methods of proving representation thecrens, such standard seriea arise. Moreover they provide a practical constructive method for finding numerical representations.

Another practical method to obtain representations from a finite sample of data uses results concerning systems of linear inequalities. If there is an order preserving, additive mapping $\hat{i}$ of $\varepsilon$. finite set $A$ into the reals, then for all $x, y, u, v \in A$, we have

$$
\text { xoy } \geqslant \text { uov iff } f(x)+f(y) \geqslant f(u)+f(v)
$$

Each inequality in the data structure defines a numerical inequality that is satisfied if the additive representation is valid. Clearly $\langle A, \geqslant, 0\rangle$ has such a representation in the reals only if the system of inequalities, defined by the ordering in the data structure, has at least one solution. An extensive literature exists on the solution, uniqueness, and algorithmic aspects of the problem of systems of Iinear inequalities.

## 2. Qualitative Probability

In probability theory the principal primitive notion is that of an 'event' usually interpreted to be a subset of the universal set or sample space $X$. To cope effectively with infinite sample spaces, it has proved necessary to restrict the system of events so as not to include all subsets of $X$. Specifically, we confine ourselves to a non-empty system $\mathcal{E}$ of subsets of $X$ that satisfies the following conảitions:
i) if $A \in \mathcal{E}$, then $\mathbb{E} \in \boldsymbol{\varepsilon}$;
ii) if $A, B \in \xi$, then $A \cup B \mathcal{E}$.

Such a system is called an algebra of subsets. It follows from i) and ii) and non-emptiness, that $X=A \cup \bar{A} \in \mathcal{E}$ and so by i), $\varnothing=\bar{X} \in \mathcal{E}$; moreover, if $A, B \in \mathcal{E}$, then $A \cap B \in \boldsymbol{\xi}$ since $A \cap D=\overline{\bar{A} \cup \bar{B}}$. If the unions of countable collections of events are also events, $\mathcal{E}$ is called a $\sigma$-algebra.

A (finitely additive) probability space is defined to be a triple $\langle X, \xi, P\rangle$, for which $\mathcal{E}$ is an algebra of subsets of $X, P$ is a measure from $\varepsilon$ into Re, i.e., for all $A, B \in E$,
i) $P(A) \geqslant 0$;
ii) if $A \cap B=\varnothing$ then $P(A \cup B)=P(A)+P(B)$;
and $P$ is a probability measure in the sense that also
iii) $P(x)=1$.

This definition of a probability space and the interpretation of probability as a measure is due to Kolmogorov (1933).

The question "what is probability?" has given rise to controversies among frequentists, objectivists, Bayesians, subjectivists, logicists, etcetera. I feel that the question is of no different character from any other measurement question, such as "what is mass?". Indeed, one can imagine equally heated debates over tine answer to that question, although they have not actually occurred. Alternatively, perhaps the arguments about probability are misplaced and it, too, should be treated as another problem of fundamental measurement. The controversies are due to the fact that whenever relative frequencies cennot be used, the most common measuring instrusent in probability measurement is the all too variable human being.

The formal measurement problem of finding necessary and sufficient conditions for the existence of an order-preserving mapping of a system $\langle x, \mathcal{Z}, \geqslant\rangle$ into a probability space $\langle X, \xi, P\rangle$ requires the existence of a weak ordering, $\geqslant$, of qualitative probability on $\mathcal{E}$. Sone ways in which this weak ordering of events can be obtained give rise to terms such as "subjective" or "intuitive" probability. These terms may prove misleading because they suggest an inherent subjectivism which, in fact, probably only reflects the present state of the art. The ways to assess $\geqslant$ inay alter with the development of the science, just as it has with other measurements. At one time the only instrument for comparing the mass of difierent objects must have been
the human being. Gradually, man was replaced by more satisfactory - more consistent, reliable, precise - instruments, such as the pan balance, the carefully subdivided ruler, etc. So far in probability measurement, no really adequate instruments have been devised except when events are highly repeatable or when certain types of arguments based on physical symmetry are possible.

Observe that there already is a iair amount of stracture in the system $\langle X, \mathcal{E}, \geqslant\rangle$. Besides $\rangle \geqslant$ being a weak order, we have assumed that $\mathcal{E}$ is an algebra of subsets. We start our axiomatization with de Finetti's (1937) 'requirements for a qualitative probability structure:
$i) \geqslant$ is a weak order over $\varepsilon$,
ii) $A \geqslant 0$ for all $A \in \xi$, and $X>\varnothing$,
iii) for all $A, B, C, D \in \mathcal{E}$ if $A \cap B=\varnothing, C \cap D=\varnothing$ and $A \sim C$, then $B \geqslant D \operatorname{iff} A \cup B \geqslant C U D$.

The conditions are clearly necessary for the existence of the required numerical probability measure, but they are not suffecient. This was proved by Kraft, Pratt and Seidenberg (1959), who constructed the following ingeneous counter-example.

Suppose that $X$ is the five-element set $\{a, b, c, d, e\}$, and $\mathcal{E}=2^{X}$ ( $=$ set of all subsets of $X$ ). We first note that if $\geqslant$ is a qualitative probability for which there is a representation, then from

$$
\begin{aligned}
\{a\} & >\{b, d\} \\
\{c, d\} & >\{a, b\} \\
\{b, e\} & >\{a, d\}
\end{aligned}
$$

it follows that

$$
\{c, e\}>\{a, b, d\}
$$

The proof is very easy. Replace the three inequalities by their numerical analogues in the representation, e.ge, $\{a\}>\{b, d\}$ by $P(\{a\})>P(\{b\})+P(\{d\})$. Add these three inequalities and cancel the same terms from both sides of the resulting inequality.

This yields $P(\{c\})+P(\{e\})>P(\{a\})+P(\{b\})+P(\{d\})$, from which $\{c, e\}>\{a, b, d\}$ follows.

Now suppose that we have some measure for which these four inequalities'hold and for which there is no set $A \in E$ with $P(A)$ between $P(\{c, e\})$ and $P(\{a, b, d\})$. For example, with $0<\mathcal{E}<1 / 3$, it is easy to see that the following measure will do:

$$
\begin{aligned}
& P(\{a\})=(4-\varepsilon) /(16-3 \varepsilon), \\
& P(\{b\})=(1-\varepsilon) /(16-3 \varepsilon), \\
& P(\{c\})=2 /(16-3 \varepsilon), \\
& P(\{a\})=(3-\varepsilon) /(16-3 \varepsilon), \\
& P(\{e\})=6 /(16-3 \varepsilon) .
\end{aligned}
$$

Since the ordering $\geqslant$ induced by $P$ satisfies the axioms of qualitative probability, so do those of $\geqslant *$ which is obtained from $\geqslant$ by keeping everything else the same except $\{a, b, d\} \geqslant *\{c, e\}$. Obviously, $\geqslant *$ does not have a numerical representation since it violates the above four inequalities.

This makes it clear that more is needed to prove a representation theorem. One of the things that we need is an Archimedean axiom (though it is not enough, since it is satisfied in any finite system such as the Kraft et al. example). To formulate this, we need the following definition:
A sequence of events $A_{1}, \ldots, A_{1}, \ldots \in \mathcal{E}$ is called a standard sequence relative to $A$ if there exist $B_{1}, C_{i} \in \mathcal{E}, i=1,2, \ldots$, such that
i) $\mathrm{A}_{1}=\mathrm{B}_{1}$ and $\mathrm{B}_{1} \sim \mathrm{~A}$
ii) $B_{i} \cap C_{i}=\varnothing$
iii) $B_{i} \sim A_{i}$
iv.) $C_{i} \sim A$
v) $A_{i+1}=B_{i} \cup C_{i}$.

This inductive definition does not make the system unbounded since, for each $A_{i}$, we still have $X \geqslant A_{i}$. We state the Archimedean axiom as:
iv) For each $A>0$, any standard sequence relative to $A$ is Einite.

We can now continue in one of two quite different ways. The first,
due to Scott (1964), is to state necessary and sufficient conditions for the finite case by using the linear inequality technique mentioned in the previous section on extensive measurement. The other, followed by Koopman (1940a, 1940b, 1941), de Finetti (1937), Savage (1954), and Luce (1967), involves simpler sufficient conditions but includes a rather strong existence (solvability) axiom. The first three authors postulated that there are partitions of $X$ into arbitrarily many equiprobable events. The latter used instead:
v) for all $A, B, C, D \in \mathcal{E}$, if $A \cap B=\varnothing, A>C$ and $B \geqslant D$, then there exist $C^{\prime}, D^{\prime}, E \in \varepsilon$, such that
a) E~AUB,
b) $C^{\prime} \cap D^{\prime}=\varnothing$,
c) $E \supseteq C^{\prime}$ and $E \supseteq D^{\prime}$,
d) $C^{\prime} \sim C$ and $D^{\prime} \sim D$.

This axiom postulates the existence somewhere else in the space of disjoint, probability-equivalent copies of the not necessary disjoint sets $C$ and D. Moreover, these copies are included in a copy of the union of two other disjoint sets $A$ and $B$ that are more probable than $C$ and D. Axioms i)-v) together are sufficient for the existence of a probability measure. One. proof first introduces a restricted concatenation operation as follows: If $\widetilde{A}$ denotes the equivalence class containing $A$, then let

$$
\mathcal{B}=\left\{(\widetilde{A}, \widetilde{B}) \mid A>\varnothing, B>\varnothing, \text { and } \exists A^{\prime} \in \widetilde{A}, B^{\prime} \in \widetilde{B} \nexists A^{\prime} \cap B^{\prime}=\varnothing\right\}
$$

When both $A$ and $B$ are very probable, they cannot be concatenated because no pair of events indifferent to the ( $A, B$ ) pair will be disjoint. We now define the concatenation operation

$$
\circ: \beta \rightarrow \varepsilon / \sim
$$

by

$$
\widetilde{A} \circ \widetilde{B}=\widetilde{A^{\prime} U B^{\prime}}
$$

By the definition of $\mathcal{\beta}$, concatenation is restricted, essentially, to disjoint events.

Theorem 2.1: If $\langle x, \varepsilon, \geqslant\rangle$ satisfies axiom i)-v), then $\langle\mathcal{E} / \sim, \beta, \geqslant, 0\rangle$ is an extensive system (i.e. a positive, solvable, Archimedean, weaklyordered local semigroup).

Surprisingly enough, the only tricky part of the proof is to show associativity. It follows immediately from Theorem 1.3 that a measure $P$ exists, and by Axiom ii) we may choose its unit so that $P(X)=1$. Thus $P$ is unique. An extension of this theory to a weak ordering of conditional events, i.e. of the form $A|B \geqslant C| D$, can be found in Luce (1968). The big problem there is that we must construct both the multiplicative structure inherent in the conditional probability representation, i.e.,

$$
\begin{equation*}
p(A \mid B)=\frac{p(A \cap B)}{p(B)} \geqslant \frac{p(C \cap D)}{p(D)}=p(C \mid D) \text { iff } A|B \geqslant C| D, \tag{1}
\end{equation*}
$$

and, at the same time, the usual additivity of probability, i.e.,

$$
\begin{equation*}
p(A \cup B)=p(A)+p(B), \text { if } A \cap B=\varnothing . \tag{2}
\end{equation*}
$$

Additivity is established by showing that the orcering induced by $A|X \geqslant B| X$ on $\mathcal{E}$ satisfies the above unconditional axioms. The conditional axioms are also showr to lead, via extensive measurement theory, to a representation satisfying eq. (1) which is unique up to $£$ positive power. The main difficulty in the proof is to show that the probability of eq. (2) is the same as one of the family satisfying eq. (1). Techniques of functional equations are used to show this.

## 3. Positive Difference Structures

A possibie task for measurement theoreticians in the behavioral sciences is to try to reduce the natural formulation of their problems to cases of extensive measurement. A useful trick, it turns out, is to reduce them to the special case of extensive measurement known as positive difference structures. These structures can best be exemplified by an axiomatization of length measured on a long (possibly infinite) ruler.

If we compare length with mass, one of the main differences not captured by extensive measurement is the fact that length is naturally isomorphic with intervals on the real line. Intervals can be characterized by their endpoints, and the concatenation of adjacent intervals is especially natural: $a b o b c=a c$. The concatenation of nonadjacent intervals, such as $a b$ and $c d$, has no comparable direct definition and one of our problems is to formulate an indirect one. Each interval can be identified in two ways: as ab and as ba. There
is, however, a natural interpretation of direction, which leads to calling one a positive interval and the other negative. We will attead only to a subset, which will be called $A^{*}$, of the positive intervals.

The primitives for our axiom system are an abstract set $A$, a set $A^{*} \subset A \times A$, which will be axiomatized in such a way as to be interpreted as a set of positive intervals, and $\geqslant$, an ordering on $A^{*}$, i.e. a subset of $A x A x A x A$. The axioms are:
i) $\left\langle A^{*}, \geqslant\right\rangle$ is a weakly ordered set;
ii) if $a b, b c, a^{\prime} b^{\prime}, b^{\prime} c^{\prime} \in A^{*}$ and if $a b \geqslant a^{\prime} b^{\prime}$ and $b c \geqslant b^{\prime} a^{\prime}$, then
a) ac, $a^{\prime} c^{\prime} \in A^{*}$, and
b) $a c \geqslant a^{\prime} c^{\prime} ;$
iii) if $a b, b c \in A^{*}$ then $a c>a b, b c ;$
iv) if $a b, c d \in A^{*}$ and $a b>c d$, then $\exists c^{\prime}, d^{\prime} \in A \ni a d^{\prime} \sim c^{\prime} b \sim c d$,
v) for $a l 1$ ab, $b c, a b^{\prime}, b^{\prime} c \in A^{*}$, if $a \sim^{\prime} b^{\prime} c$, then $a b^{\prime} \sim b c$.

Axioms ii)-v) have a very simple interpretation in terms of length, and can be illustrated by drawing a line with the relevant points on it. In such a structure, a sequence $a_{1}$, ..., $a_{i}, \ldots \in A$ with $\left(a_{i+1}, a_{i}\right) \in A^{*}$, for all i, is called a standard sequence iff there exists an $a b \in A^{*}$ such that $a_{i+1} a_{i} \sim a b$ for each $i$.

$$
\text { vi) } \frac{\text { If }}{\text { (Archimedean axiom). }}\left\{a_{i}\right\} \text { is a siandard sequence, then }\left\{n \mid n \in I^{+}, c d \geqslant a_{n} a_{1}\right. \text { is finite }
$$

We now define
$B=\left\{(\widetilde{a}, \widetilde{c}, \tilde{d}) \mid J a^{\prime}, b^{\prime}, c^{\prime} \in A \ni a^{\prime} b^{\prime}, b^{\prime} c^{\prime} \in A^{*} \Lambda a b \sim a^{\prime} b^{\prime} \Lambda c d \sim b^{\prime} c^{\prime}\right\}$ And iff $(\widetilde{a b}, \widetilde{c d}) \in B$, then $\widetilde{a b} \circ \widetilde{c d}=\widetilde{a^{\prime} c^{\prime}}$.

Theorem 3.1: If $\left\langle A, A^{*}, \geqslant\right\rangle$ satisfies axiorns i)-vi), then $\left\langle A^{*} \mid \sim, B, \geqslant, 0\right\rangle$ is an extensive system, provided that there exist $a b, c d \in A^{*}$ such that $a b>c d$.

Corrollary 3.2: There exists a real-valueç, order preserving mapping $\psi$ on $A^{*} \mid \sim$ which is unique up to multiplication by a positive real number.

Corrollary 3.3: If $a, b \in A$, if not $a c \sim b c$ for all $c \in A$, and if for all $a, b, \in A^{*}$ either $a b \in A^{*}$ or $b a \in A^{*}$, then there exists a function $\varphi: A \rightarrow R e$, such that

$$
\psi(a b)=\varphi(a)-\varphi(b) ;
$$

moreover, $\varphi$ is unique up to a positive linear transformation.

## 4. Additive Conjoint Measurement

For most attrioutes of interest in the behavioral sciences no natural concatenation operation is available. This means that the direct use of extensive measurement is impossible. If we accept N.R. Campbell's dictum "fundamental measurement = extensive measurement", then fundamental measurement is impossible in the behavioral sciences. This conclusion was reached after careful deliberation by the members (among them Campbell) of a British committee who investigated the possibility of measurement in psychology. It has proved far too pessimistic and premature since, in recent years, a number of quite different, but equally fundamental, systems have been proposed, among them conjoint measurement, the topic of this section, and subjective expected utility, the topic of the 6 th one. In conjoint measurement no concatenation operation is assumed, but another kind of structure having to do with the fact that most attributes can be manipulated by several independent variables, sometimes permits representations of the following type.

Let $\geqslant$ be an ordering of a Cartesian product ${ }_{i=1}^{n} A_{i}$, where each $A_{i}$ is a set. Such a structure is called decomposable relative to (a real-valued function) $\mathrm{F}: R \mathrm{e}^{\mathrm{n}} \rightarrow$ Re if there exist functions $\varphi_{i}: A_{i} \rightarrow R e, i=1, \ldots, n$, such that for all $\left(a_{1}, \ldots, a_{n}\right),\left(b_{1}, \ldots, b_{n}\right)$ $\in \prod_{A_{i}}:$
$\left(a_{1}, \ldots, a_{n}\right) \geqslant\left(b_{1}, \ldots, b_{n}\right)$ iif $F\left(\varphi_{1}\left(a_{1}\right), \ldots, \varphi_{n}\left(a_{n}\right)\right) \geqslant F\left(\varphi_{1}\left(b_{1}\right), \ldots, \varphi_{n} b_{n}\right)$.

Phis definition expresses the fact that the contributions of the variablas to the overall measure are independent of one another. This
is a very general requirement, but it is by no means a trivial one, since f.t is not satisfied in $\begin{gathered}\text { anses. For example, suppose that }\end{gathered}$ $n=2$ and let $\varphi_{i}: A_{i} \rightarrow R e$ and $\psi_{i}: A_{i} \rightarrow \operatorname{Re}$ for $i=1$, 2, be given functions. For all $a, b \in A_{1}, p, q \in h_{2}$, define the ordering $\geqslant$ on $A_{1} \times A_{2}$ by

$$
\begin{aligned}
(a, p) \geqslant(b, q) \text { iff } \varphi_{1}(a)+\varphi_{2}(p) & +\psi_{1}(a) \psi_{2}(p) \\
& \geqslant \varphi_{1}(b)+\varphi_{2}(q)+\psi_{1}(b) \psi_{2}(q)
\end{aligned}
$$

This "additive structure with independent interaction" is not in general decomposable relative to aily function. In spite of the natural interest in this model as, perhans, the simplest form of interaction, we know nothing about its properties. No necessery conditions (except weak ordering) have been discovered.

The only two-component cases* so far investigated are the additive one, $F(x, y)=x+y$, and the multiplicative one, $F(x, y)=x y$. In general, the multiplicative model can not be reduced to an additive one by a logarithmic transformation because the scale values may be negative. In the three-component case, the functions $F(x, y, z)=x+y+z$, $x y z,(x+y) z$, and $x+y z$, are thoroughly investigated. In the sequel we will confine ourselves to the n-component additive case.

The most familiar example of an additive model is, of course, the one from economics that says that the cardinal utility of a comodity bundle is equal to the sum of the utilities of each of its components. As a matter of fact this model inspired much of the earlier work on additive conjoint measurement (cf., for example, Debreu, 1960). In psychology a two-dimensional example is obtained if we let subjects compare the loudness of pure tones, varying both their intensities and frequencies. In both examples it is possible to draw indifference curves to represent the equivalence classes in the data structure. The theory establishes a systematic way to associate numbers with the indifference curves that, in a sense, represent the amount of attribute exhibited by that curve.

An example where this has been done successfully (but independently of the theory, I must admit) can be found in studies of Campbell and Masterson (1968) on the aversiveness of shocks. On one side of a shuttle box they placed shock with resistance $Z$ and voltage $V_{Z}$, and on the other, shock with resistance $Z_{o}$ and voltage $V_{0}$. Throughout
the experiment $Z_{0}$ was held fixed, and for each ( $Z, V_{Z}$ )-pair they discovered the value of $V_{0}$ such that $50 \%$ of the animals selected each side. They found that the empirical values satisfied a relationship of the form

$$
v_{Z}=\alpha+\beta v_{0}+\gamma z+\delta v_{0} Z
$$

which is equivalent to the additive form

$$
\log \left(\delta v_{Z}+\gamma \beta-\alpha \delta\right)=\log \left(\gamma+\delta v_{0}\right)+\log (\beta+\delta z)
$$

Many other examples of trade-off between variables can be found in the literature.

In all axiomatizations of additive conjoint measurement, certain necessary cancellation conditions play an important part. One of these conditions expresses, quite directly, the fundamental independence of the variables: for all $a, b \in A_{1}$ and $p, q \in A_{2}$,

$$
\begin{aligned}
&(a, p) \geqslant(b, p) \text { iff }(a, q) \geqslant(b, q) \\
& \text { and } \quad(a, p) \geqslant(a, q) \text { iff }(b, p) \geqslant(b, q) .
\end{aligned}
$$

Notice how this follows if an additive representation is true:

$$
\begin{aligned}
(a, p) \geqslant(b, p) & \text { iff } \varphi_{1}(a)+\varphi_{2}(p) \geqslant \varphi_{1}(b)+\varphi_{2}(p) \\
& \text { iff } \varphi_{1}(a) \geqslant \varphi_{1}(b) \\
& \text { iff } \varphi_{1}(a)+\varphi_{2}(q) \geqslant \varphi_{1}(b)+\varphi_{2}(q) \\
& \text { iff }(a, q) \geqslant(b, q) .
\end{aligned}
$$

As a matter of fact this condition justifies the natural definition of an induced order $\geqslant_{1}$ on the first dimension:
$a \geqslant_{1} b$ iff $\forall x \in A_{2}$ we have $(a, x) \geqslant(b, x)$.

Similarly, we may define $\geqslant_{2}$ on the second dimension. Another property that can be arrived at in the same way is called double canelation: for all $a, b, f \in A_{1}$ and $p, q, x \in A_{2}$,

$$
\text { if }(a, x) \geqslant(f, q) \text { and }(f, p) \geqslant(b, x) \text {, then }(a, p) \geqslant(b, q) \text {. }
$$

Other cancellation properties can be obtained by considering three or more inequalities in which all save four elements can be "cancelled". Later, we expiicitly give one of the three inherently different forms of triple cancellation. All these conditions are necessary, and all may be checked directly in any set of data. For fairly large data structures, this is a very time-consuming task; indeed, it is only practical if a computer is used.

We may, howerer, restrict the number of necessary conditions needed to get an additive representation by strenghtening the sufficient conditions that impose structure on the system. This is done in the following axiomatization of $n$-dimensional conjoint measurement, with $n \geqslant 3$. Let $A$ denote the cartesian product $\prod_{i=1}^{n} A_{i}$, when $n \geqslant 3$.
i) $\langle A, \geqslant\rangle$ is a weakly ordered set.
ii) If $N=\{1,2, \ldots, n\}$, then for all $M \subseteq \mathbb{N}$ the ordering induced on $\prod_{i \in M} A_{i}$ for any fixed choice of elements in $\prod_{i \in N-M} A_{i}$ is independent of that choice.

Ayiom ii) permits us to define $\geqslant_{i}$ on $A_{i}$ in the obvious way, and it turns out to be the only cancellation axiom that we need when $n \geqslant 3$, provided that we impose a strong solvability condition. Iuce and Tukey (1964) postulated the following solution (of equations) axiom: $\forall a, b \in A_{1}, p \in A_{2}, \exists x \in A_{2} \exists(a, p) \sim(b, x)$. This has been justly criticized as being too strong; in many examples it is easily seen not to be satisfied (e.g., loudness judgments). Therefore, Luce (1966) modified it to the following restricted solvability condition: $\forall a, b \in A_{1}, p \in A_{2}$, if $\exists \bar{x}, \underline{x} \geqslant(b, \bar{x}) \geqslant(a, p) \geqslant(b, \underline{x})$, then $\exists x \geqslant(b, x)$ $\sim(a, p)$. A simple generalization gives us
iii) For all $\left(a_{1}, \ldots, a_{n}\right) \in A,\left(b_{1}, \ldots, b_{i-1}, b_{i+1}, \ldots, b_{n}\right) \epsilon$ $A_{1} \times \ldots \times A_{i-1} \times A_{i+1} X \ldots x A_{n}$, if there exist a $\bar{b}_{i}$ and a $b_{i}$ such that $\left(b_{1}, \ldots, \bar{b}_{i}, \ldots, b_{n}\right) \geqslant\left(a_{1}, \ldots, a_{n}\right) \geqslant\left(b_{1}, \ldots, b_{i}, \ldots, b_{n}\right)$, then there exists $a b_{i}$ such that $\left(b_{1}, \ldots, b_{i}, \ldots, b_{n}\right) \sim\left(a_{1}, \ldots, a_{i}, \ldots, a_{n}\right)$

Moreover, we need a nontrivialness axiom:
iv) For at least three components $A_{i}$ there exist $a_{i}, b_{i} \in A_{i}$ such that

In order to state the necessary Archimedean axiom, we need the following definition: Let $\mathbb{N}$ be a succession of integers, positive and/or negative, finite or infinite: A sequence $\left\{a_{i}^{\gamma} \mid a_{i}^{\gamma} \in A_{i} \wedge \gamma \in \mathbb{N} \wedge \exists p, q \in A_{j}, j \neq i, \ni\right.$ $\left(\ldots, a_{i}^{\gamma}, \ldots, p, \ldots\right) \sim\left(\ldots, a_{i}^{r+1}, \ldots, q, \ldots\right)$ for $\left.\gamma, \gamma+1 \in \mathbb{N}\right\}$ is called a standard sequence. The Archimedean axiom simply is
v) Fvery bounded standard sequence is finite.

Theorem 4.1; If axioms i)-v) hold, then there exist $\varphi_{i}: A_{i} \rightarrow$ $\operatorname{Re}, i=1, \ldots ., n$, such that for $a l l\left(a_{1}, \ldots, a_{n}\right),\left(b_{1}, \ldots, b_{n}\right) \in A$,

$$
\begin{aligned}
& \left(a_{1}, \ldots, a_{n}\right) \geqslant\left(b_{1}, \ldots, b_{n}\right) \text { iff } \\
& \sum_{i=1}^{n} \varphi_{i}\left(a_{i}\right) \geqslant \sum_{i=1}^{n} \varphi_{i}\left(b_{i}\right) .
\end{aligned}
$$

Moreover, if $\varphi_{i}^{\prime}$ is another set of such functions, then $\exists \alpha>0, \beta_{i}$, $i=1, \ldots, n$, such that $\varphi_{i}=\alpha \varphi_{i}^{!}+\beta$.

Notice that we have not yet formulated a representation theorem for the two-component cases. This we must do, not only because it is of interest and importance in its own right, but also because the only known proof of the n-component case involves reducing the problem to the two-component case. There is no need to alter the weak ordering, solvability, and Archimedean axioms in the two-component case. The property of independence is, however, too weak and it is replaced by two cancellation properties, namely, double cancellation:
(ii) for all $a, b, f \in \mathbb{A}_{1}$ and $p, q, x \in A_{2}$

$$
(a, x) \geqslant(f, p) \wedge(f, p) \geqslant(b, x) \text { imply }(a, p) \geqslant(b, q)
$$

and by one of the three forms of triple cancellation:
(iii) for all $a, b, f, g \in A_{1}$ and $p, q, x, y \in A_{2}$

$$
\begin{aligned}
& (a, x) \geqslant(b, y) \wedge(f, y) \geqslant(g, x) \wedge(g, p) \geqslant(f, g) \text { imply } \\
& (a, p) \geqslant(b, q) .
\end{aligned}
$$

From these assumptions it is casily shown that independence holds and so a weak ordering is induced on each component. The final assumption is that both co-ordinates are essential. This is all that is needed.

Theorem 4.2; If $\left\langle A \cdot A_{2}\right.$, $\left.\geqslant\right\rangle$ satisfies the weak ordering, double and triple cancellation, restricted solvability, Archimedean and essentialness conditions, then the conclusion of theorem 4.1 holds with $n=2$.

It is an open problem to show that double and triple cancellation are independert axioms, or to derive one from the other.

We now outline the nature of the proofs of Theorem 4.1 and 4.2. Iet $A_{i}$ and $A_{j}$ be any two essential components in the $n$-component case. I't is easy to see that the induced crder $\geqslant_{i j}$ satisfies all of the assumptions of Theorem 4.2 except the two cancellation properties. These also follow. It is fairly difficult to prove them for restricted solvability, but easy for urıestricted. For example, suppose $a, b, f \in A_{i}$ and $p, q, x \in A_{j}$ and $(a, x) \geqslant_{i j}(f, q)$ and $(f, p) \geqslant_{i j}(b, x)$. Let $A_{k}$ be any other essential component and let $u \in A_{k}$. By solvability, $\exists v \in A_{k}$ such that

$$
(f, x, v) \sim_{i j k}(a, x, u) \geqslant_{i j k}(f, q, u),
$$

and so $(x, v) \nexists_{j k}(q, u)$. Since $(f, x, u) \sim_{i j k}(a, x, u)$, then by independence $x$ may be replaced by $p$, and so

$$
(a, p, u) \sim_{i j k}(f, p, v) \geqslant_{i j k}(b, x, v) \geqslant_{i j k}(b, q, u) .
$$

Thus, $(a, p) \geqslant_{i j}(b, q)$. The proof for triple cancellation is similar. By theorem 4.2, there exists an additive representation $\varphi_{i}+\varphi_{j}$ on $A_{i} \times A_{j}$

There is, however, a problem. Suppose we picked i, $j \in \mathbb{N}$ and found mappings $\varphi_{i}: A_{i} \rightarrow \operatorname{Re}$ and $\varphi_{j}: A_{j} \rightarrow \operatorname{Re}$. We can of course also choose another pair $i, k \in \mathbb{N}$, with $k \neq j$. This gives us the mappings $\varphi_{i}^{\prime}: A_{i} \rightarrow \operatorname{Re}$ and $\varphi_{k}: A_{k} \rightarrow \operatorname{Re}$. It must be shown that $\varphi_{i}^{\prime}=\alpha \varphi_{i}+\beta$, with $\alpha>0$. Finally, it can also be shown that if we choose our functions $\varphi_{i}$ carefully so that the units and zeroes are appropriately reiated, then this provides an additive representation. When we accept this, the problem is reduced to the two-component one.

The next step in the reduction process used to prove Theorem 4.1 is to reduce the two dimensional system of Theorem 4.2 to a special, symmetric
case. In Figure 1, the cartesien product $A_{1} \times A_{2}$ is portrayed as a rectangle, as it will be in the desired representation.


Figure 1

The points $a_{0}, a_{1}, p_{0}, p_{1}$ are chosen in such a way that $\left(a_{0}, p_{1}\right) \sim\left(a_{1}, p_{0}\right)$ and they determine the unit and the unit square consisting of all points ( $x, y$ ) for which $a_{1} \geqslant x \geqslant a_{0}$ and $p_{1} \geqslant y \geqslant p_{0}$ (the shaded area in Figure 1).

Suppose that we now want to assign a number to the point ( $a, p$ ) in Figure 1. We move unit steps in both directions until we arrive at a point in the unit square. This process is also illustrated in Figure 1. Then, of course, the sensible thing to try is the assignment:

$$
\begin{aligned}
& \varphi_{1}(a)=\varphi_{1}(a-1)+1 \\
& \varphi_{2}(p)=\varphi_{2}(p-2)+2
\end{aligned}
$$

where the coordinates ( $\mathrm{a}-1, \mathrm{p}-2$ ) are coordinates of a point in the unit square. The main part of the proof is to show that this inductive process can indecd be carried out. It relies heavily on the assumed triple cancellation and restricted versions of the other two triple cancellation conditions which can be proved from the axioms.

A system $\left\langle A_{1} \times A_{2}, \geqslant\right\rangle$ is called symmetric if for all $a, b \in A_{1}$, $\exists p, q \in A_{2} \ni(a, p) \sim(b, q)$. Such systems can be mapped into a square, whereas the general case results in a rectangle. So we are done if we can get the representation in thiscase. Define the set
$A_{1}^{*}=\left\{a b \mid a, b \in A_{1} \wedge a>_{1} b\right\}$, and define $\geqslant_{1}^{*}$ on $A_{1}{ }^{*}$ by if $a b, c d \in A_{1}{ }^{*}$, then $a b \geqslant_{1}{ }^{*}$ od iff $\forall p, q \in A_{2}$ whenever

$$
(a, p) \sim(b, q), \text { then }(d, q) \geqslant(c, p)
$$

Do the same thing for the second coordinate, which gives an $A_{2}^{*}$ and a $\geqslant_{2}{ }^{*}$. Now it can be proved that $\left\langle A_{1}, A_{1}{ }^{*}, \geqslant_{1}{ }^{*}\right\rangle$ and $\left\langle A_{2}, A_{2}{ }^{*}, \geqslant_{2}{ }^{*}\right\rangle$ satisfy the axioms for positive difference systems, so by corrolary 3.3 (previous section)

$$
\begin{aligned}
\exists \varphi_{1}: A_{1} & \rightarrow \operatorname{Re}, \varphi_{2}: A_{2} \rightarrow \operatorname{Re} \ni \\
\mathrm{ab} & \geqslant_{1}^{*} \text { cd iff } \varphi_{1}(\mathrm{a})-\varphi_{1}(\mathrm{~b}) \geqslant \varphi_{1}(\mathrm{c})-\varphi_{1}(\mathrm{~d}) \\
\mathrm{pq} & \geqslant 2_{2}^{*} \text { uv iff } \varphi_{2}(\mathrm{p})-\varphi_{2}(\mathrm{q}) \geqslant \varphi_{2}(\mathrm{u})-\varphi_{2}(\mathrm{v})
\end{aligned}
$$

Moreover we pick an $a_{1}>a_{0}$ and $p_{1}>p_{0}$ such that $\left(a_{0}, p_{1}\right) \sim\left(a_{1}, p_{0}\right)$ and we set $\varphi_{1}\left(a_{0}\right)=\varphi_{2}\left(p_{0}\right)=0$ and $\varphi_{1}\left(a_{1}\right)=\varphi_{2}\left(p_{1}\right)=1$, and define $\psi_{1}(a b)=\varphi_{1}(a)-\varphi_{1}(b), \psi_{2}(p q)=\varphi_{2}(p)-\varphi_{2}(q)$. The next thing to be established is that the two systems $\left\langle A_{1}, A_{1}{ }^{*}, \geqslant_{1}{ }^{*}\right\rangle$ and $\left\langle A_{2}, A_{2}^{*}, \geqslant 2^{*}\right\rangle$ have essentially the same structure.
Define: $\quad \theta(\widetilde{a k})=\widetilde{q p}$ iff $(a, p) \sim(b, q)$,
then it is shown that $\theta$ is an isomorphism, and that $\psi_{1}=\psi_{2}(\theta)$. The final step in the proof of Theorem 4.2 is simple: It just remains to be proved that the $\psi^{\prime}$ s are order preserving. Observe that

$$
\begin{aligned}
\varphi_{1}(a)+\varphi_{2}(p) \geqslant \varphi_{1}(b)+\varphi_{2}(q) & \text { iff } \varphi_{1}(a)-\varphi_{1}(b) \geqslant \varphi_{2}(q)-\varphi_{2}(p) \\
& \text { iff } \psi_{1}(\widetilde{a b}) \geqslant \psi_{2}(\widetilde{q p}) \\
& \text { iff } \psi_{1}(\widetilde{a b}) \geqslant \psi_{2}(\theta(\widetilde{c d})), \text { where }(c, p) \sim(d, q) \\
& \text { iff } \psi_{1}(\widetilde{a b}) \geqslant \psi_{1}(\widetilde{c d}) \\
& \text { iff } \widetilde{a b} \geqslant \geqslant_{1}^{*} \widetilde{c d} \\
& \text { iff }(a, p) \geqslant(b, q)
\end{aligned}
$$

## 5. Bisymmetry Systems

A theory due to Pfanzagl, which assumes a concatenation operation, can be reduced to additive conjoint measurement. His theory is similar to extensive measurement, but it is more general in that, among other things, it axiomatizes the formation of weighted means. Suppose that $\rho$ is a fixed number in $[0,1]$ and for any real numbers $a, b$, we define $a \circ b=\rho a+(1-\rho) b$. We see that $o$ has many properties different from extensive measurement. For example, a 0 ana, 0 is not commutative, and 0 is not associative.
Pfanzagl begins with a structure $\langle A, 0, \geqslant\rangle$ and he assumes:
i) $\langle A, \geqslant\rangle$ is a weakly ordered set,
ii) $a \geqslant b$ inf $a \circ c \geqslant b \circ c \wedge c \circ a \geqslant c \circ b$,
iii) A is connected in the order topology induced by $\geqslant$,
iv) $\mathrm{a} \circ \mathrm{b}$ is continuous in both a and b ,
v) $(a \circ b) o(\operatorname{cod}) \sim(a \circ c) o(b o d)$.

This last axiom, the bisymmetry axiom, does not imply that the system is associative and/or commutative. Observe that this axiom is true for weighted means. Pfanzagl proved the following result:

Theorem 4.3: If $\langle A, 0, \geqslant\rangle$ satisfies axioms i)-v), there exist real numbers $\rho ; \sigma>0, \lambda$ and a function $\varphi: A \rightarrow \operatorname{Re}$ such that
i) $a \geqslant b$ ff $\varphi(a) \geqslant \varphi(b)$,
ii) $\varphi$ is continuous,
iii) $\varphi(\mathrm{aob})=\rho \varphi(\mathrm{a})+\sigma \varphi(\mathrm{b})+\lambda$,
iv) if $\varphi^{\prime}$ also satisfies i) -iii) then $\varphi^{\prime}=\alpha \varphi+\beta$, with $\alpha>0$.

Corrollary 4.3:
i) if aoama, then $\lambda=0$, and $\rho+\sigma=1$
ii) if the structure is commutative, then $\rho=\sigma=1$
iii) if it is both commutative and associative, then $\rho=\sigma=1$, and $\lambda=0$

In the last case we have extensive measurement (set $\psi=\varphi+\lambda$ ). In the first case we have the weighted mean interpretation. The proof of the theorem can be carried out by reducing it to the twodimensional additive conjoint case.

Define

$$
(a, p) \geqslant(b, q) \quad \text { iff } \quad a \circ p \geqslant b \circ q
$$

The various axioms of theorem 4.2 must be proved. We establish double cancellation as an example: suppose $(a, x) \geqslant(f, q)$ and $(f, p) \geqslant(b, x)$, then by definitior aox $\geqslant f o q$ and fop $\geqslant$ box. Now consider

$$
\begin{array}{rll}
(\text { aop }) \circ(x \circ x) \sim(a \circ x) \circ(\text { pox }) & (\text { by bisymmetry }) \\
\geqslant(f \circ q) \circ(p \circ x) & (\text { by monotonicity }) \\
& \sim(f \circ p) \circ(q \circ x) & (\text { by bisymmetry }) \\
\geqslant(b \circ x) \circ(q \circ x) & (\text { by monotonici } i v) \\
& \sim(b \circ q) \circ(x \circ x) & \text { (by bisymmetry) }
\end{array}
$$

It follows by monotonicity and transitivity of $\geqslant$ than íaop) $\gtrsim$ (boq), hense $(a, p) \geqslant(b, q)$. The proof of triple cancellation is somewhat more complicated, but similar. The most difficult part is to derive the solvability and Archimedean conditions from the tupclugiceal axioms (iii) and iv). This can ke done.

## 6. Conditional Expected Jtility Theory

Expected utility theories attempt to describe the behavior of a rational decision maker when confronted with choices among uncertain prospects. The principal primitive notions are "event" and "consequence". An "uncertain prospect" or "gamble" consists of a finite number of chance events, say $e_{1}, \ldots e_{n}$, and a consequence associated with each event, denoted by $c_{1}, \ldots, c_{n}$. Expected utility theories construct two real-valued functions: a utility function $u$ that maps the set of consequences into the reals and a probability measure $P$ that is defined on the events. The expected utility $E U$ is computed by taking expectations:

$$
E U=\sum_{i=1}^{n} u\left(c_{i}\right) P\left(e_{i}\right)
$$

and it orders gambles in the same way as do the preferences of the rational decision maker.

The first modern discussion of expected utility theory is in an appendix of the 1947 edition of Von Neumann and Morgenstern's classic book. They were concerned with simple gambles in which consequence a arises with probability $p$ and consequence $b$ with probability $1-p$. The probabilities
were assumed to je given in a numerical form. Such a gamble can be written as apb. Von Neumann and Morgenstern also introduced a compounding operation that makes it possible to construct more complicated gambles, such as (apb)qc, from simple ones. They axiomatized an ordering $\geqslant$ over simple gambles and simple compounds of them. The axioms they introduced garanteed the existence of an order-preserving numerical expected utility function. The construction of this function depended on the numerical values of the objective probabilities, which obviously means that their procedure is not an example of fundamental measurement. Blackwell and Girshick, Samuelson, and others generalized this approach to n-component gambles (cf. Luce end Raiffa, 1957). A much deeper generalization was provided by Savage (1954), who completely dropped the objective probability assumption. He invroduced axioms that are sufficient for the existence of both a subjective probability measure $P$ and a utility $u$ with the property that a gamble $f$ is preferred to a gamble $g$ if and only if the subjective expected utility of + is greater than the subjective expected utility of g. Savage's theory is vcry general, but as we shall see it has certain unnotural features.

Another line of development was initiated by the philosopher Ramsey (1931) whose idear, were worked out in detail by Suppes and his collaborators (cf. Davjdson snd Suppes, 1956). The main difference from Savage's approach is that Ramsey firat constructed a utility function, from which a probability function is then developed; whereas, Savage begen with axioms sufficient for the existence of a (subjective) probability measure, and he then defined utilities in terms of these probabilities (as Von Neumann and Morgenstern did in terms of objective probabilities). The Ramsey-Suppes-DavidsonWinet approach is still restricted to very simple, two-component gambles with independent events. Pfanzagl (1967) generalized this in such a way that compounding of non-independent events became possible. A still more general treatment of the problem is given by Luce and Krantz (1968). Not only does their axiom system cover general gambles as well, but a more general representation is obtained which also generalizes some ideas of Jeffrey. Sckematically this historical discussion may be summarized as follows:


In comparing Savage's statistical decision theory with the Juce-Krantz conditional theory, it is important to recognize that in most cases of prastical interest people think in a conditional way. If you want.to decide whetrer to go to Paris by plane or by car, for example, the reasoning is typically conditional. When considering the events that can arise When going by car, the fact that the plane nay crash is simply not relevant. It is, of course, when considering the possible eve_ts associated with the flight. Moreover, the unconditional formulation of decision theory in the Savage-approach is highly inefficient. Consider the following simple example, in which there are two gambles: the first one is the throw of a die (D)

| erent | 1 | 2 | 3 | 4 | 5 | 6 |
| :---: | ---: | :---: | :---: | :---: | :---: | :---: |
| consequence | -3 | -2 | -1 | 1 | 2 | 3 |

The second one is the throw of a coin (C)

| event | Head Tail |
| :---: | :---: |
| consequence | 10 |$-10$

In the Savage formulation we must consider the complete cartesian product of states of nature and list all outcomes.

|  | 1 H | 1 T | 2 H | 2 T | 3 H | 3 T | 4 H | 4 T | 5 H | 5 T | 6 H | 6 T |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D | -3 | -3 | -2 | -2 | -1 | -1 | +1 | +1 | +2 | +2 | +3 | +3 |
| 0 | +10 | -10 | $+i 0$ | -10 | +10 | -10 | +10 | -10 | +10 | -10 | +10 | -10 |

In the conditional formulation, we list all possible consequences and for each decision list the events that cause each to arise:

|  | -10 | -3 | -2 | -1 | 1 | 2 | 3 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $D$ | $\phi$ | 1 | 2 | 3 | 4 | 5 | 6 | $\phi$ |
| $C$ | $T$ | $\phi$ | $\phi$ | $\phi$ | $\phi$ | $\phi$ | $\phi$ | $H$ |

Of course the information in these two schemes is the same, but evidently the Savage notation is the more redundant, even in this simole example.

That the two approaches can be translated into each other in the finite case may not be clear at first sight. To show it, we first list the primilives of the statistical approach: a set $\mathcal{S}$ of states of nature, a set $\tau$ of consequences, and mappings of the form $f: \mathcal{S} \rightarrow \tau$. 'she representation involves two functions, a utility $u: \tau \rightarrow R e$ and a probability $Q:$
$S \rightarrow[0,1]$, and subjective expected utility is defined as $\sum_{i} u\left[f\left(s_{i}\right)\right] Q\left(s_{i}\right)$. The summation is over all states of nature.

In the conditional approach, the primitives are a set $X$, en algebra $\mathcal{Z}$ of subsets of $X$, a set of consequences $\tau$, and mappings $f_{A}: A \rightarrow \tau$ for $A \in \mathcal{E}$. The representation yields $u: \tau \rightarrow R e$, and $P: \varepsilon \rightarrow[0,1]$, and the expected utility is defined as $\Sigma u\left(c_{i}\right) P\left[f_{A}^{-1}\left(c_{i}\right) \mid A\right]$, where the summation is over all consequences. The translation of the statistical theory into the conditional is trivial: define $X=S ; \xi=2^{\rho} ; f_{X}=f ; P=Q ;$ and $u=u$. The translation from the conditional to the statistical theory is less obvious. Define $\mathcal{S}=\prod_{A_{i} \in \varepsilon} \quad A_{i} ; Q\left(s_{i}\right)=\prod_{\ell}\left[P\left(s_{i}^{\ell}\right) \mid P\left(A_{\ell}\right)\right]$, where $s_{i} \in \mathcal{S}$,ie.
$s_{i}=\left(s_{i}^{1}, \ldots, s_{i}^{\ell}, \ldots, s_{i}^{\ell}\right) ; f\left(s_{i}\right)=f_{A}\left(s_{i}^{\ell}\right)$ where $l$ is the index such that ${ }^{A}{ }_{\ell}=A ;$ and $u=u$. One then shows that the latter expectation implies the former.

The primitives of the Iuce-Krantz axiomatization are as follows. First, we have an algebra of subsets $\varepsilon$ of some abstract set $X$. Moreover, a subset $\eta \subseteq \mathcal{\varepsilon}$ must be characterized by the axioms. Intuitively, the elements of $\eta$ can be thought of as those events that are judged as having no probability of occurring. We condition only on events in $\mathcal{\varepsilon}-\eta$ to avoid division by 0 in the representation. Again $\tau$ denotes the set of consequences. The decisions are a set of functions $D \subseteq\left\{f_{A} \mid f_{A}: A \rightarrow \tau\right.$, $A \in \mathcal{E}-\eta\}$. Finally we have a binary relation $\geqslant$ on $D$. Decisions can be compounded in the following way: if $A \cap B=\varnothing, A, B \in \varepsilon-\eta, f_{A}, g_{B} \in \mathcal{D}$ then $f_{A} \cup_{g_{B}}(x)=\operatorname{def} \begin{cases}f_{A}(x) & \text { if } x \in A . \\ g_{B}(x) & \text { if } x \in B \in B \subseteq A \text { and } B \in \mathcal{E}-\eta, \text { then }\left(f_{A}\right)_{B}\end{cases}$ denotes the restriction of $f_{A}$ to the set $B$. The axioms of a conditional decision structure can now be stated as follows.
For all $A, B \in \mathcal{Z}-\eta, f_{A}, f_{A}, g_{B} \in D$
i) a. $A \cap B=\varnothing \Rightarrow f_{A} \cup g_{B} \in D$

$$
\text { b. } \mathrm{B} \subseteq \mathrm{~A} \quad \Rightarrow \quad\left(\mathrm{f}_{\mathrm{A}}\right)_{\mathrm{B}} \in \mathcal{D}
$$

ii) $\langle\mathcal{D}, \geqslant\rangle \quad$ is a weakly ordered set.
iii) $A \cap B=\varnothing \wedge f_{A} \sim g_{B} \Rightarrow f_{A} \cup g_{B} \sim f_{A}$.

$$
\text { iv) } A \cap B=\emptyset, \quad f_{A} \gtrsim f_{A}^{\prime} \Leftrightarrow f_{A} \cup g_{B} \gtrsim f_{A}^{\prime} \cup g_{B^{\prime}}
$$

This last axiom bears an obvious resemblance to the monotonicity condition in extensive measurement ( $\hat{i}$. section 1, axiom vi). Moreover, the famous sure-thing principle is is special case of axiom iv. The sure-ining grinsiple asserts that if $\mathrm{fO}_{\star}$ each possible outcome the consequence of gamble $f$ is preferred or indifferent to the consequence of gamble gand for at least one outcome it is strictly preferred, then gamble $f$ will be premferred to gamble g.

For our next axiom we need the following definition: a sequence
 $\ni A \cap B=\varnothing \wedge \exists g_{B}(0), g_{B}(1) \in D \exists \forall i, i+i \in N, f(i) \cup g_{B}(1) \sim \pm A_{A}(i+1) \cup g_{B}^{(0)}$. The Archimedean axioll is as usual:
v) every bounded standard sequence is finite.

Moreover, we use the notion of a standard sequence in:

$$
\begin{aligned}
& \text { vi) }\left\{f_{A}^{(i)} \mid N\right\},\left\{h_{A}^{(i)} \mid N\right\} \text { are s.3. } \backslash \exists k, k+1 \in N \ni f_{A}^{(k)} \sim h_{A}^{(k)} \Lambda \\
& \mathbf{f}_{A}^{(k+1)} \sim_{h_{A}}^{(k+1)} \Longrightarrow \forall \pm \in N, f_{A}^{(i)} \sim_{h_{A}}^{(i)} .
\end{aligned}
$$

Our next axiom characterizes the set $\eta$.
vii) a. $R \in \eta \wedge S \subseteq R \Rightarrow S \in \eta$. b. $\left.\Leftrightarrow \nLeftarrow \mathbf{I}_{A \cup R} \sim{ }^{\prime} \mathbf{I}_{A \cup R}\right)_{A}$.

The next axiom is a non-triviality assumption.
viii) a. $\varepsilon-\eta$ has at least three pairwise disjoint elements. b. J/ $\sim$ has at least two equivalence classes.

The final axiom ia similar to the solvability axioms that we have presviously used in the other measurement models. Suppose that $A, B \in \mathcal{E}=\eta$. $h(1), h(2), g_{B}, f_{A \cup B} \in D$,
ix) a. $\exists h_{A} \in \mathcal{D} \Rightarrow h_{A} \sim g_{B}$.
b. $A \cap B=\varnothing \wedge_{h_{A}}(1) \cup_{g_{B}} \gtrsim f_{A \cup B} \gtrsim h_{A}(2)_{\cup_{B}} \Rightarrow \exists h_{A} \in ग \ni$ $h_{A} \cup g_{B} \sim f_{A} \cup B^{\bullet}$

Clearly the first part of axiom ix) is a form oi s unrestricted aolvability, and this is one part of the axiom system that we would really like to
weaken. Surprisingly enough, the second part of axiom ix) is independent of the first part, although it is rather like the restricted solvability assumption we made in additive conjoint meesurement.

Theorem 5.1: If $\langle x, \varepsilon, \eta, \tau, D, \geqslant\rangle$ setispies axioms i)-ix), then there exist functions $u: D \rightarrow$ Re and $P: \varepsilon \rightarrow[0,1]$ such that, for all $f_{A}, g_{B} \in D$,
a. $\langle X, \varepsilon, F\rangle$ is a finjtely additive probability space.
b. $R \in \eta \Leftrightarrow P(R)=0$.
c. $\quad f_{A} \geqslant g_{B} \Leftrightarrow u\left(f_{A}\right) \geqslant u\left(g_{B}\right)$.
d. if $A \cap B=\varnothing$, then $u\left(f_{A} \cup g_{B}\right)=u\left(f_{A}\right) P(A \mid A \cup B) \therefore u\left(g_{B}\right) P(B \mid A \cup B)$.
e, $P$ is unique, and $u$ is unique up to a positive linear transformation.

There are some important differences from Savage's result. In the first place, the utility function is not defined on the set of consequences. As a matter of fact, we could even do without $\tau$ since the axioms nowhere refer to $\tau$. Part $d$. of theorem 5.1 does not say that $u$ is an expectation in the statistical sense; it has a major property of an expectation, but only under very special conditions is it actually one. The infiniteness of Savage's system is explicitly built into the set of states. The infiniteness of the Luce-Krantz system is in the set of ecisions, but not necessarily in $\mathcal{E}$; the algebra of subsets $\mathcal{E}$ is only specified to be non-empty. A serious weakness in the statistical approach is the essential role in the construction of $u$ and $P$ that is played by constant decisions, i.e. decisions that hafe same consequence independent of the state of nature. Constant decisions may be realizable in aimple situavions, but they are very unreailstic in realistic settings. It can be shown that there is a realization of the Luce-Krantz system in which there are no constant decisions. ''o get a utility function over $\tau$, let $c_{A}$ denote the constant decision with $f_{A}(x)=c$ for all $x \in A$. If we add the following assumptions,
x) $c \in \tau \Rightarrow J A(c) \in \varepsilon-\eta \ni c_{A(c)} \in D$
xi) $c_{A}, c_{B} \in J \Rightarrow c_{A} \sim c_{B}$
to axioms i)-ix), then it follows that there exists $v: D \rightarrow$ Re such that for any gamble $f_{A} \in D, u\left(f_{A}\right)=E\left[v\left(f_{A}\right) \mid A\right]$, where $E$ denotes taking expuctations. A gamble is a decision with a finite image and for c $\in \mathcal{T}$
$f_{A}^{-1}(c) \in \varepsilon$. Note that assumption $x$ ! is trivially true if, for example, the toss of a coin is included in $\mathcal{E}$; it is much weaker than assuming that all constant decisiuns are in $D$. Another important case, not admissible under Savage's axioms; is where the utility of $\varepsilon$ decision has contributions from both the consequences and the conditioning event. For example, suppose that $w: ~\} \rightarrow R e$ is such that for $A \cap B=\phi$, $w(A \cup B)=w(A) P(A \mid A \cup B)+w(B) P(A \mid A \cup B)$, and $v: \tau \rightarrow R e$, then $a$ utility for gambles may be defined as $u\left(f_{A}\right)=E\left[v\left(f_{A}\right) \mid A\right]+w(A)$. This more realistic model, whick can be interpreted as admitting utility-for-gambling, is consistent with axiom i)-x) but, of course, not with Xi) except when w 三0.

Savage's method of proof was to obtain subjective probabilities, from which he constructed the utility function along the lines of Von Neumann and Morgenstern's proof. In our approach $P$ and a come out simultaneously. We briefly sketch the nature of the proof. Take an arbitrary non-null event $A$ and partition it into con-null sets $A_{i}, i=1, \ldots$, . . Let $\int_{A_{i}}$ denote the subset of $D$ whose elements are defined on $A_{i}$. Define

$$
\geqslant 1 \text { or } \prod_{i} \int_{A_{i}}:
$$

$$
\left(f_{A_{1}}, f_{A_{2}}, \ldots, f_{A_{n}}\right) \geqslant \geqslant_{1}\left(g_{A_{1}}, g_{A_{2}}, \ldots, g_{A_{n}}\right) \Leftrightarrow f_{A_{1}} \cup f_{A_{2}} \cup \ldots \cup f_{A_{n}} \geqslant g_{A_{1}} \cup g_{A_{2}} \cup \ldots \cup g_{A_{n}}
$$

It is possible to show that in $\left\langle\Gamma_{i} T J_{A_{i}}, \geqslant_{1}\right\rangle$ the axioms of n-dimensional conjoint measurement are satisfied (if $n=2$ we have io ke careful, but startm ing with a more refined partitioning of $A$ makes $n \geqslant 3$ again). Therefore
$\exists \varphi_{i}: I_{A_{i}} \rightarrow R e$, and these functions are, of course, order-preserving and unique up to positive linear transformations. A different partitioning defines other functions, but they can ive shown to be of the same family. We have to pick $q$ particular one: if $f^{(1)}>f^{(0)}$, then for any $\Lambda$ there exist $g \mathcal{A}^{(1)} \sim \mathcal{f}^{(1)}$ and $g \mathcal{A}^{(0)} \sim_{f}(0)$. Zero and unit are eatablished by picking $u_{A}$ so that $u_{A}\left(g A_{A}(0)=0\right.$ and $u_{A}\left(g \AA^{(1)}\right)=1$. For any $\mathcal{D}_{A}$, this defines a unique $u_{A}$. And because $D$ is the union of the $D_{A}$, let $u$ on $D$ be the union of all these functions. For $A \cap B=\phi$, we have
$u\left(f_{A} \cup g_{B}\right)=\varphi_{A}\left(f_{A}\right)+\varphi_{B}\left(g_{B}\right)=P(A \mid A \cup B) u\left(f_{A}\right)+\beta_{A, B}+P(B \mid A \cup B) u\left(g_{B}\right)+\beta_{B, A}$, where $\varphi_{A}\left(f_{A}\right)=P(A \mid A \cup B) \cup\left(f_{A}\right)+\beta_{A, B}$ is simply the linear transformation that relates $\varphi_{A}\left(f_{A}\right)$ and $u\left(f_{A}\right)=u_{A}\left(f_{A}\right)$. It remains to be proved, that the P-values are conditional probabilities, that $\beta_{B, A}+\beta_{A, B}=0$, and that $u$ is
order-preserving. Since $g(0) \sim f(0) \sim g_{A}(0)$, we also have $g(0) \cup g_{B}(0) \sim f_{f}(0)$, so $u\left(g A_{A}^{(0)} \cup g_{B}^{(0)}\right)=0=P(A \mid A \cup B) u(g(0))+P(B \mid A \cup B) u\left(g_{B}^{(0)}\right)+\beta_{A, B}+\beta_{P, A}=$ $0+0+\beta_{A, B}+\beta_{B, A}$. By using the $g(1)$-elements in a similar way, we establish that the $P^{\prime}$ s are conditional probabilities. Tre proof that $u$ is order-preserving is rather difficult.

Although this is nerhaps the most satisfactory existing axiomatization of subjective expected $\mathfrak{i t i n t y , ~ s o m e ~ i m p r o v e m e n t s ~ a r e ~ c l e a r l y ~ p o s s i b l e . ~}$ First axi om ix) A cather strong; we especially would like to weaken part a). Seconi, some data and examples suggest that the sure-thing principle is nct a very good description of actual decision making (although it cervainly stems rational to many people, though not to all). And finally, in the algebra $\mathcal{E}$, ail events are treated as equally realizable: and i'vaj be usaful to partition $\varepsilon$ into those that are realizable and thoso tinat are only usel for mathematical purposes. For example, the subevents of f . planc 1 ? ight and of $a$ car trip seem more natural conditioning events for decis: onf rian Hoes, say, the event \{plane arrives 3 hrs. late, auto amines on iire $\}$. T'le peculjar structure of $\varepsilon$, in which all events are treated alike, may eren be related to the violations of the sure-thing principle.

## Concluding Note

In these lectures we have discussed a number of different examples of fundamental measurement. They are summarized in the following diagram, in which the reductions used to prove the representation and uniqueness theorems are indicated by arrows.


This is not the only possible hierarchy of axiom systems. Pfanzagl, for example, reduces all systems he investigates to bisymmetry structures.

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